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AFAPL-TR-67-125  
PART I

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## SIMULATION OF TURBOFAN ENGINE

### PART I. DESCRIPTION OF METHOD AND BALANCING TECHNIQUE

JOHN S. MCKINNEY, CAPTAIN, USAF

TECHNICAL REPORT AFAPL-TR-67-125, PART I

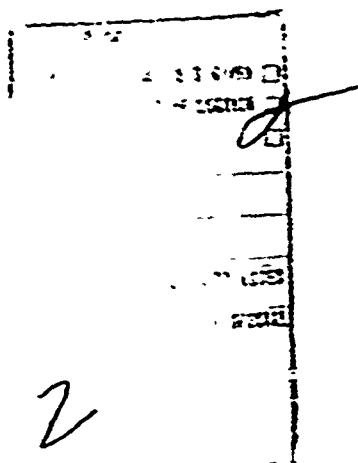
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AFAPL-TR-67-125  
PART I

## **SIMULATION OF TURBOFAN ENGINE**

### **PART I. DESCRIPTION OF METHOD AND BALANCING TECHNIQUE**

**JOHN S. McKINNEY, CAPTAIN, USAF**



AFAPL-TR-67-125

Part I

#### FORWORD

This report was prepared in the Components Branch (APTC), Turbine Engine Division, Air Force Aero Propulsion Laboratory, Wright-Patterson Air Force Base, Ohio, under Project 3066, "Gas Turbine Technology," Task 306603, "Advanced Engine Studies," with Charles E. Bentz as Project Engineer.

This report covers work conducted within the Components Branch in the time period between July 1965 and June 1967 and was submitted by the author 31 August 1967.

This technical report has been reviewed and is approved.

*Ernest C. Simpson*  
ERNEST C. SIMPSON  
Chief, Turbine Engine Division  
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## ABSTRACT

This report describes a digital computer program titled SMOTE (Simulation of Turbofan Engine). SMOTE is a computer program for balancing-cycle turbofan engines capable of running both design and off-design points. Component performance maps are reduced to Block Data (tabular form) to provide a base for calculating component performance. The design point is run first and map correction factors are calculated to scale the components to the desired performance. These correction factors are then applied to the component performance maps at off-design points. Initially, in the program is running at an off-design point, the cycle is not balanced, and errors (for example, work required by the compressor minus work supplied by the turbine) are generated. Small changes in engine independent variables (for example, compressor speed) then produce small changes in the errors, and these differential changes are loaded into a matrix. The matrix is then solved for the set of independent variables which results in zero errors, thus balancing the cycle. Actually, this process may be repeated several times before it reaches a balanced point because there is a nonlinear relationship between the independent variables and the errors. Sample results are included in this report.

(Distribution of this abstract is unlimited.)

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## SYMBOLS

BLF	bleed from fan lost to cycle (leakage)
BLDU	bleed from compressor to duct (leakage)
BLHP	bleed from compressor to high pressure turbine (cooling)
BLLP	bleed from compressor to low pressure turbine (cooling)
BLOB	bleed from compressor overboard for customer use
CN	corrected speed
DHTC	delta-H corrected for temperature
H	enthalpy
PCNC	percent speed of the compressor
PCNF	percent speed of the fan
P	pressure
P2	pressure at the fan face
TFFHP	turbine flow function, high pressure turbine
TFFLP	turbine flow function, low pressure turbine
T	temperature
T2	temperature at the fan face
T21	temperature at the fan exit
T4	main combustor burning temperature
T24	duct-burner burning temperature
T7	afterburner burning temperature
WFA	afterburner fuel flow
WFB	main-combustor fuel flow
WFD	duct-burner fuel flow
WG	gas flow rate
ZC	pressure-ratio ratio of the compressor
ZF	pressure-ratio ratio of the fan

## SECTION I

### INTRODUCTION

Recent advances in turbine-engine state of the art have increased the requirements for more and better cycle studies. These cycle studies are needed to monitor present engines, determine sensitive or critical areas in near future engines now under development, and to explore the advantages and disadvantages of proposed advanced engine cycles for future aircraft.

Parametric cycle studies, which involve essentially numerous design-point calculations, partially fulfill this need, particularly for optimizing a cycle for a specific single design-point mission. However, with multimission aircraft being emphasized increasingly and with the need for determining off-design performance, the requirement for a balancing cycle computer program (that is, one which simulates a turbine engine at both design and off-design points) becomes definite and essential.

The purpose of this report is to describe a digital computer program for balancing-cycle turbofan engines. The program, titled SMOTE (Simulation of Turbofan Engine), was developed in the Components Branch, Turbine Engine Division, Air Force Aero Propulsion Laboratory, to meet the requirements given in the preceding paragraphs. In addition to meeting these requirements, SMOTE is considerably more flexible, requires less computer storage or space, and requires less computer operating time than previous engine cycle decks of comparable sophistication.

Part I of this report describes the method of engine calculations and the balancing technique and gives some sample results. Part II is intended as a user's manual and includes instructions for setting up and running the program, as well as a program listing. The parts may be used independently of one another.

## SECTION II

### SUMMARY

SMOTE is a computer program for balancing-cycle turbofan engines which presently uses component performance maps for the fan, compressor, combustor, and both turbines to provide the basic performance data, but it can easily be expanded to include additional component performance maps if available. The maps are in Block Data form and are scaled internally to simulate a specific engine. Errors due to an unbalanced cycle are generated at off-design points, and the effects of small changes in independent variables upon the errors are determined. A matrix of differential error equations is then solved to determine the correct values of the independent variables which would produce zero errors. A flow chart of the program is shown in Figure 1.

For a more accurate simulation of a particular engine, performance maps for other components could be added; for example, duct-burner or afterburner maps may be desired. It should also be mentioned that other formats for presenting maps may be used as readily as those presented in this report. Rather than inputting bleed air values at each point or using a constant bleed, a bleed schedule could be used. In addition, if a variable-area nozzle is to be simulated, a nozzle area schedule could be used. Or an engine control system could be used which would set fuel flow, bleeds, and nozzle areas as some function of a power lever angle.

The complexity of an engine cycle can be increased by increasing the size of the matrix (increasing the number of partial differential equations). For example, a basic triple-spool turbofan cycle could be represented using a matrix of nine equations. Or a T-compressor fan engine composed of a fan tip, fan hub, low pressure compressor (running at the same speed as the fan), high pressure compressor, combustor, two turbines, gas mixer, and afterburner could be represented using a matrix of eight equations.

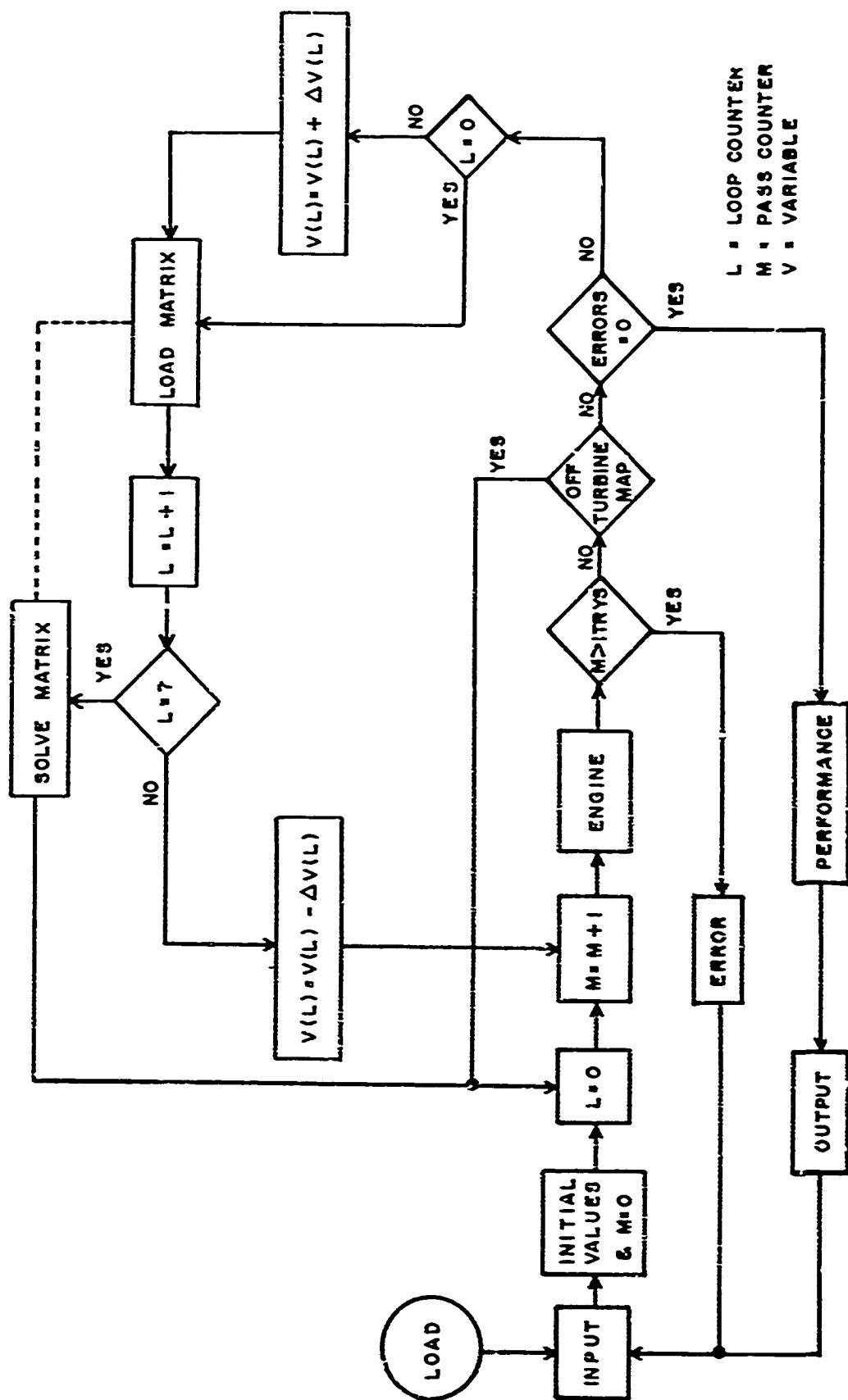


Figure 1. SMOKE Computer Program Flow Chart

## SECTION III

### HISTORY

Until about six years ago, most general cycle calculations in the Components Branch were done by hand, although some computer programs were available for specific engines. About that time a turbojet, parametric-cycle study program (SPEEDY) was conceived, and, from this program, a more general turbojet or turbofan program (CARPET) with many configuration options was developed. CARPET is still in general use for parametric and optimization studies.

About three years ago, a balancing-cycle turbojet or single-spool computer program (SSPOOL) was developed within the Components Branch. The engine component calculations were based essentially on those in CARPET, and the balancing technique, which depended upon a quadratic interpolation routine (AFQUIR), involved two nested balancing loops. The inner loop was balanced using PCNC as an independent variable and the work difference between compressor and turbine as the dependent variable. The outer loop was balanced using ZC (see Figure 2 for a definition of ZC) and the pressure required by the fixed-area exhaust nozzle. After the inner loop was balanced, the outer loop was changed in an attempt to balance it. Naturally, changes in the outer loop necessitated rebalancing the inner loop. This method, although rather crude, worked well for a turbojet cycle.

The SSPOOL concept was then extended to a turbofan or dual-spool cycle which resulted in a new program called DSPOOL. By logical extension this required four nested loops with four independent variables (PCNF, ZF, PCNC, and ZC) and four dependent variables or errors (two work errors and two nozzle pressure errors for a separate flow cycle; or two work errors, a mixing static pressure error, and a nozzle pressure error for a mixed flow cycle). Although the method worked, computer time was excessive, and various techniques (such as changing the order of the independent variables or using a varying tolerance) were tried in an attempt to shorten the balancing time. These attempts were only partially successful.

Other balancing techniques using various mathematical solutions were experimented with, and the present method was finally developed. This method involves no nested balancing loops; instead, a matrix is loaded with differential errors caused by small changes in the independent variables. The matrix is then solved for the zero error condition. SMOTE reduced computer time by an average factor of about 4 as compared to DSPOOL.

## SECTION IV

### METHOD OF ENGINE CALCULATIONS

#### 1. COMPONENT MAPS

The performance of the major engine components is based on component maps. These maps are usually obtained from analytical methods or rig-testing and are then converted into Block Data subroutines for use by SMOTE. The maps presently included in SMOTE are very general and do not represent any particular engine or engine components.

The component maps are scaled at the engine design point by SMOTE in order to match their performance to a desired set of performance figures which are input as data. Scaling or correction factors are calculated and then applied to the maps at off-design points. The scaling process is linear; therefore correction factors near unity result in the highest accuracy of component simulation. This means that the component maps used should represent or be similar to the actual components in the engine being simulated. However, with the loss of a little accuracy, maps representing advanced components could be interchanged to determine the effect on the overall cycle.

SMOTE presently includes component maps for the fan, compressor, combustor, and both turbines. Duct burning, duct losses, gas mixing, afterburning, tailpipe losses, and nozzle losses are all calculated or input, but these characteristics could also be included as Block Data if maps were available. Likewise, schedules for bleed air and variable area nozzles could be used.

##### a. Fan-Compressor Maps

The fan and compressor maps are very similar and are plots of corrected airflow versus pressure ratio with constant corrected speed lines and constant efficiency islands (see Figure 2). Entry to the map is through the corrected speed and  $Z$ , where  $Z$  is a pressure-ratio ratio, and is defined at a constant corrected speed as shown in Figure 1. It is advantageous to use  $Z$  instead of pressure ratio because  $Z$  is restrained between the limits of 0 and 1, whereas the limits on the pressure ratio vary depending upon map location and the particular map. Also, an indication that the fan or compressor is approaching surge is given as  $Z$  approaches 1.

##### b. Combustor Map

The combustor map is a plot of temperature rise across the combustor versus efficiency for constant input pressure (see Figure 3). Entry to the map is through temperature rise and input pressure, with efficiency being output.

##### c. Turbine Map

The turbine map is a plot of turbine corrected speed versus work function with constant turbine flow function lines and constant efficiency islands (see Figure 4). The work function and flow function are defined as

$$DHTC = \frac{H_{IN} - H_{OUT}}{T_{IN}}$$

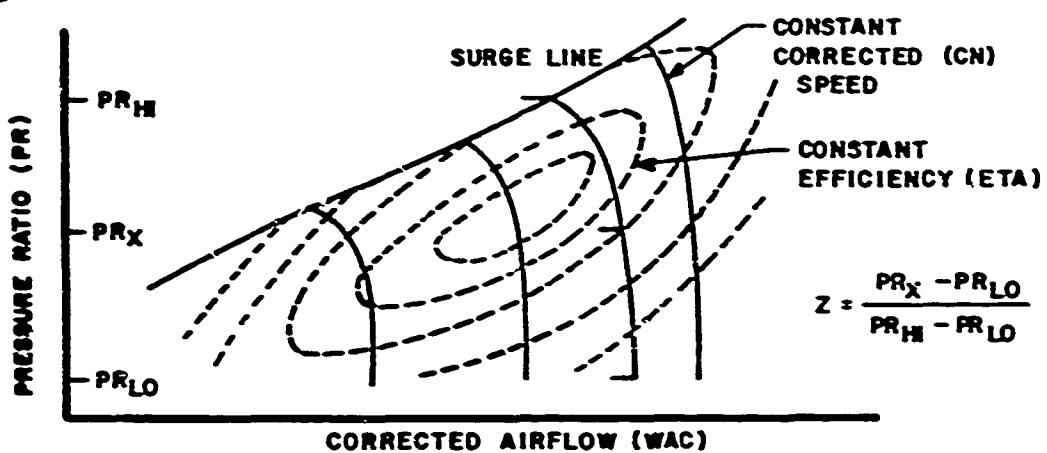


Figure 2. Example of Fan-Compressor Map

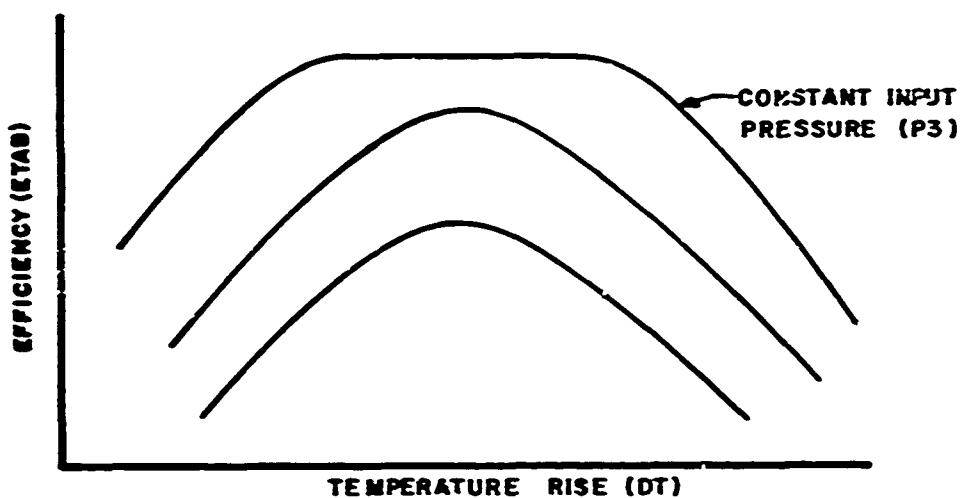


Figure 3. Example of Combustor Map

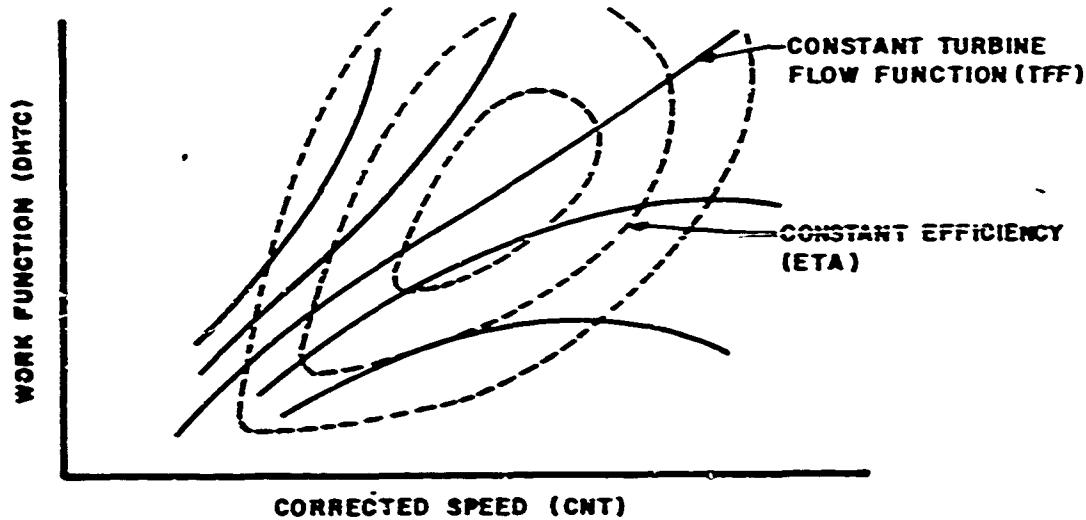


Figure 4. Example of Turbine Map

and

$$TFF = \frac{WG_{IN} \sqrt{T_{IN}}}{P_{IN}}$$

Entry to the map is through corrected speed and turbine flow function, with the work function and efficiency being output.

The work function could have been used as an entry in place of one of the present entries, but, because of the shape of the curves, this could lead to double entry points for one work function. However, if the turbine maps were plotted in a different format, this could be an acceptable method.

## 2. DESIGN POINT

Once the component maps have been reduced to Block Data form and placed in the program, it is necessary to run a design point. The design point is run at those conditions under which the real engine is designed or sized, usually sea level static. Design parameters necessary to simulate the real engine (for example, airflow, bypass ratio, main burner temperature, various pressure losses, pressure ratios, etc.) are input and a complete thermodynamic cycle calculation is performed. For more details on the cycle calculation see Section IV 4, "Off-Design Points." Scale factors for the component maps are calculated to insure that the input design parameters are met. If the design parameters have been correctly input, the design point will be completed after one pass through the engine calculations (that is, no balancing will occur) because the maps are shifted to reduce the errors to zero.

Other parameters calculated and output at the design point include certain temperatures and airflows, gas mixing areas, and nozzle throat and exit areas.

## 3. SCALING FACTORS

Scaling or correction factors are calculated at the design point using the following equation:

$$P(\text{correction factor}) = P(\text{design}) / P(\text{map})$$

where P represents a general parameter. One exception to this equation is the equation for calculating fan and compressor pressure correction factors:

$$PR(\text{correction factor}) = [PR(\text{design}) - 1] / [PR(\text{map}) - 1]$$

where PR represents a general pressure ratio.

Theoretically, if the component maps and the input design parameters are exact representations of a particular engine, the correction factors will equal 1. However, this will not be true due to map interpolations, certain assumptions such as ideal and isentropic flow, and tolerances in the thermodynamic calculations. The correction factors should be within 1% of 1. Naturally, if unmatched component maps are used, the correction factors can differ significantly from 1.

## 4. OFF-DESIGN POINTS

The following discussion pertains particularly to off-design points, although the input and the general cycle calculations are the same for the design point. Throughout the following discussion, it should be remembered that scaling or correction factors (multipliers) are applied to all performance maps (Block Data parameters).

For more detailed information on the thermodynamic equations used throughout the cycle calculations, see References 1, 2, and 3 and Part II of this report. A schematic diagram of the engine components and station designations is shown in Figure 5.

#### a. Input

The program uses a controlled output; that is, the variables desired as output can be selected at the start of a run. This selection is obtained by placing the names of the variables in the first section of input cards. Controls, scaling or correction factors, and operating conditions make up the rest of the input.

The control inputs are used to determine the type of engine: mixed flow or separate flow, afterburning, duct burning, and convergent or convergent-divergent nozzles. The controls are also used to fix the mode of operation: constant PCNC, constant T4, or constant WFB. Other controls determine inlet conditions, title printout, and cycle looping printouts. The correction factors can be input directly, or the design point can be run first and the calculated factors will be left in common. The operating conditions include the flight Mach number, altitude, power setting (either PCNC, T4, or WFB), duct burner and afterburner temperatures or fuel flows, bleed, and horsepower extracted.

#### b. Initial Values

The program uses four primary independent variables: ZF, PCNF, ZC, and PCNC (T4 may be substituted for PCNC, depending upon the mode of operation). Two secondary independent variables (TFFHP and TFFLP) are also used to insure correct entry into the turbine maps. Initial values for these six variables must be obtained to start the program at each point. A subroutine supplies these variables as a function of T2, T21, and some of the variables themselves. It is important to note that the closer the initial values are to the final values at a balanced point, the faster the program will run. Therefore, after a particular engine configuration has been run a few times, it is usually advisable to change the general initial value equations to suit the engine, using the knowledge gained from past runs to estimate more closely the final values of the variables.

#### c. Inlet

The thermodynamic properties of the atmosphere are found from a 1962 ARDC Atmosphere Tables subroutine. Using conservation of energy and isentropic flow, the conditions at the face of the fan can be found. A ram recovery (total pressure recovery) can be input or, if not input, a ram recovery defined by Mil-E-5008B Specifications will be used. If desired, a T2-P2 direct input mode is available, as are provisions for nonstandard day conditions.

#### d. Fan and Compressor

Block Data is used to determine the performance characteristics of the fan and compressor. When Z and PCN are known, the pressure ratio, corrected airflow, and efficiency can be found by using a general Block Data interpolation routine named SEARCH. With the pressure ratio known and when the assumption of isentropic compression and the efficiency are used, the thermodynamic conditions at the exit of both the fan and the compressor can be calculated. Bleed for consumer use, leakage, or cooling is accounted for. Actual airflow leaving the fan and the compressor is calculated from the corrected airflow, temperature, pressure, and bleed.

#### e. Combustor

The pressure drop in the combustor is a function of a design pressure drop and the ratio of corrected airflow to the design corrected airflow. Combustor efficiency is obtained from

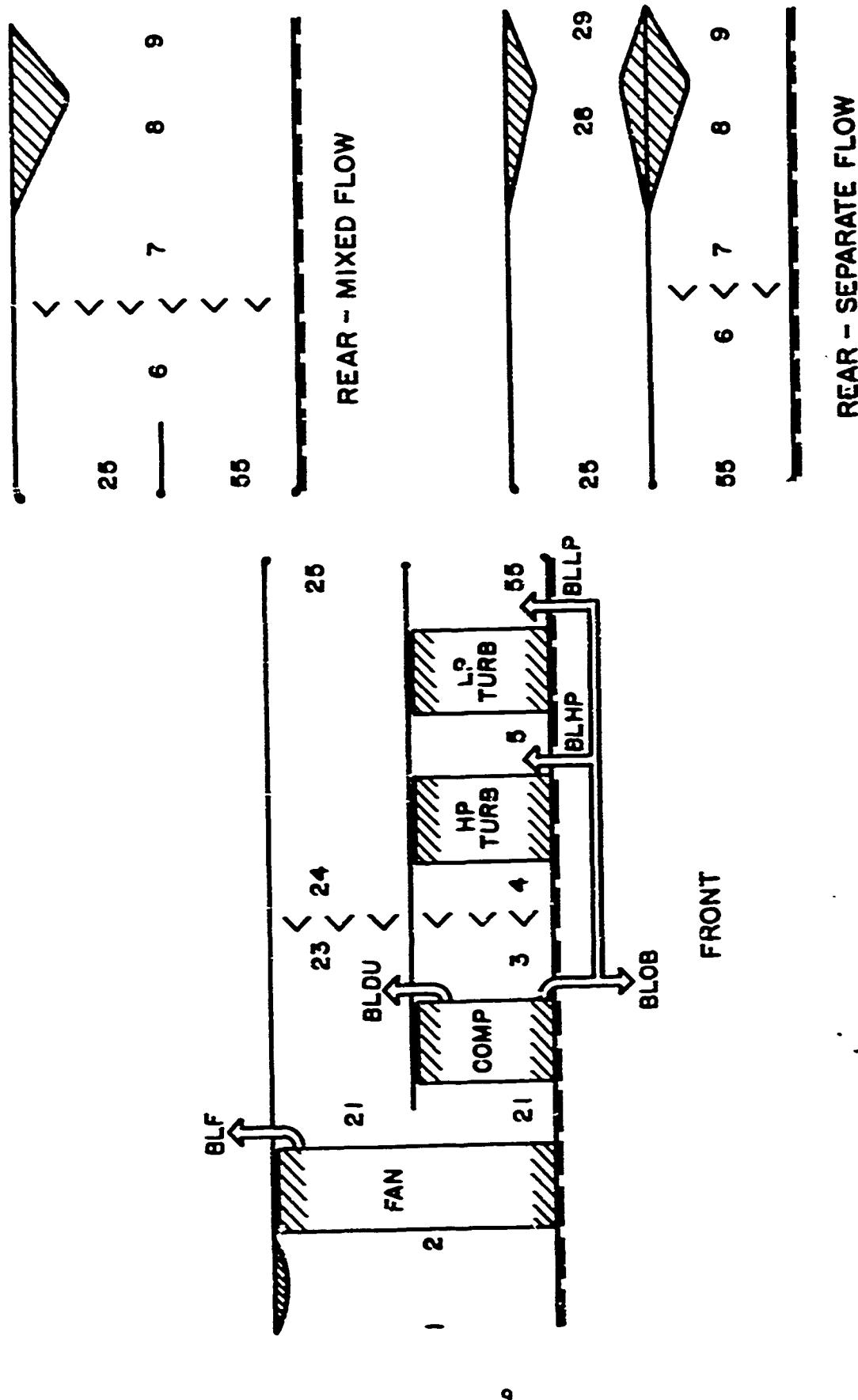


Figure 6. Schematic of Engine Components

Block Data using SEARCH. The fuel used is assumed to be JP-4 (at 59°F), and, with the assumption of adiabatic and constant pressure combustion, a fuel heating value equation as a function of T4 has been derived. Thus the fuel/air ratio, fuel flow, and thermodynamic conditions at the combustor exit can be calculated. If WFB is known instead of T4, a small iteration is necessary.

### f. Turbines

Both turbine subroutines use similar logic and obtain their performance characteristics from Block Data using subroutine SEARCH. All three turbine parameters (CN, TFF, DHTC) can be calculated before entering the turbine map, but only two are needed. Therefore, the third parameter obtained from the map is compared with the calculated third parameter, and a balancing error is generated if they are not equal. In this program, CN and TFF are used for map entries, and DHTC is used to generate the error. In addition, the efficiency is also obtained through SEARCH.

In addition, another error will be generated if TFF is not within map limits. The error will be the difference between TFF and the nearest map limit. This error becomes particularly important when the estimated initial values of the independent variables are far from the correct values, and the point is extremely unbalanced. When either TFF or CN is not within map limits, they are set to the nearest map limit, and one of the independent variables is changed in an attempt to rectify the situation. The operating point must appear on all maps before a complete cycle calculation can be accomplished.

Horsepower extraction is accounted for in calculating DHTC of the high pressure turbine. When the efficiency is used and the turbine process is assumed isentropic, the thermodynamic properties at both turbine exits can be calculated. Any bleed airflow for cooling the turbines is treated as if it entered the main stream behind the turbine, and the thermodynamic properties at the turbine exits are recalculated to account for this.

### g. Duct

The duct airflow and bypass ratio are calculated from the fan and compressor airflows. The pressure drop in the duct is treated as in the main combustor. For duct-burning, the same fuel heating value equation that was used in the combustor is again used, but the efficiency must be input. As in the combustor, either the temperature (T24) or the fuel flow (WFD) may be input.

If a separate flow engine is being simulated, the duct nozzle calculations are done in this routine, although they are accomplished in the same manner as for the main nozzle.

### h. Mixer

The gas mixing areas (duct exit and turbine discharge for a mixed flow engine or just the turbine discharge area for a separate flow engine) are calculated at the design point using either an input static pressure or Mach number. At an off-design point the areas are used to calculate static pressures and Mach numbers.

For a separate flow engine, the thermodynamic conditions entering the afterburner are now known, since they are identical to turbine discharge conditions.

For a mixed flow engine, a set of derived equations based on one-dimensional fluid flow theory and conservation of mass, energy, and momentum is used to determine the thermodynamic conditions after complete mixing of the two gas streams (Reference 4). These equations do not require that the static pressures of the two entering streams be equal. However, for a correct engine balance, the two static pressures must be equal, and a balancing error is generated if they are not equal.

### i. Afterburner

The dry loss (cold loss) pressure drop in the afterburner is a function of a design pressure drop and the ratio of corrected gas flow to the design corrected gas flow.

For afterburning, the same equation for the fuel heating value that was used in the combustor is again used, but the efficiency must be input. As in the combustor, either the temperature ( $T_7$ ) or the fuel flow ( $W_{FA}$ ) may be input. A momentum loss (hot loss) pressure drop is also calculated.

### j. Nozzle

The main nozzle program uses fixed effective areas (except when afterburning) calculated at the design point. Either a convergent or a convergent-divergent subroutine may be used depending upon the input controls. If afterburning has been selected, the nozzle areas are allowed to float to obtain optimum performance; however the areas are returned to their original design values after the afterburning point is completed. The duct nozzle behaves identically with the main nozzle, including floating areas if duct-burning has been selected.

Because all thermodynamic properties of the gas stream are known, as well as the amount of flow, nozzle areas, and ambient pressure, there is a redundant parameter. For this program, the total pressure of the gas stream was chosen as the redundant parameter. The nozzle calculations (Reference 5) are made without using the total pressure, and a required total pressure compatible with all other known parameters is calculated. This required pressure is compared with the actual pressure, and a balancing error is generated if they are not equal.

### k. Performance and Output

At this point, six errors have been generated after one pass through the engine. Several more passes must be completed under control of the error matrix and engine balancing subroutines. See Section V for a detailed description of the balancing technique used. Eventually, however, the errors will be reduced to zero, and engine performance will be calculated using standard equations. Gross thrust is obtained by summing the momentum term (a nozzle velocity coefficient may be input) and pressure-area term, and net thrust is in turn found by subtracting a ram drag (airflow momentum loss at inlet) term from the gross thrust. Specific fuel consumption is total fuel flow divided by net thrust.

As previously mentioned, a controlled output is used, whereby only selected variables are printed. Each variable is labeled with its name, and provisions have been made for changing the name of a variable. In addition, the values of all variables in common are printed in a close format so that variables other than those selected for a specific run are available later on.

## 5. QUADRATIC INTERPOLATION ROUTINE

Throughout the program there are many small loops (for example, thermodynamic iterations and table look-up) which require convergence. Trial-and-error methods and linear interpolations can be time-consuming, especially when a tight tolerance is necessary; therefore a general interpolation routine called AFQUR (Air Force Quadratic Interpolation Routine) was developed.

This routine requires a dummy array dimensioned for nine locations. Also input into the routine through the calling argument are the independent and the dependent variables, the answer or value which the dependent variable is to converge upon, the number of tries at convergence, the tolerance, and a variable called DIR.

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The DIR is either set or calculated in the calling program and is an initial guess at the direction and percentage change to apply to the first value of the independent variable. If not enough is known about the variables to calculate a DIR, an arbitrary value may be set. This should not affect the final result, but may increase the number of tries at convergence.

The DIR thus establishes the second value of the independent variable. This value is used in the calling program to determine a corresponding second value of the dependent variable and AFQUIR is called a second time with two sets of values. A linear interpolation is made which results in a third value of the independent variable. AFQUIR is then called a third time with the third values of independent and dependent variables and a quadratic interpolation is made. The values of these three sets of variables have been stored in the dummy array, and from here on, quadratic interpolations are made using the three sets which give values closest to the answer. Values farthest from the answer are lost.

Various safeguards are built into AFQUIR to return the interpolation method to DIR or linear if the roots of the quadratic become complex, if the quadratic does not intercept the answer, if the value of the independent variable differs radically from previous values, or if two sets of independent and dependent variables are identical.

Also, it is possible to preload the dummy array and to start directly at the linear or quadratic interpolations if desired.

In summary, AFQUIR is a completely flexible routine which performs quadratic interpolation for quick convergence of general functions.

## SECTION V

### BALANCING TECHNIQUE

The balancing technique is based upon finding a solution for a set of partial differential equations. For this program, the set is composed of six equations; however, using a set of only three equations will simplify the following discussion. This corresponds to a basic turbojet engine simulation. It is relatively easy to expand the set of three equations to one of six, as required in SMOTE, or even further. For example, a triple-spool turbofan would require nine equations.

As discussed previously, six independent variables were selected (ZF, PCNF, ZC, PCNC or T4, TFFHP, and TFFLP). Once these variables have been given initial values, it is possible to proceed through an entire engine cycle calculation. Six errors are generated as shown in Section IV. These initial values of the six variables and six errors are referred to as base values.

In the following equations, V refers to a variable and E to an error. The basic set of differential equations based on  $E = f(V)$  is (Reference 6)

$$\begin{aligned} dE_1 &= \frac{\partial E_{11}}{\partial V_1} dV_1 + \frac{\partial E_{12}}{\partial V_2} dV_2 + \frac{\partial E_{13}}{\partial V_3} dV_3 \\ dE_2 &= \frac{\partial E_{21}}{\partial V_1} dV_1 + \frac{\partial E_{22}}{\partial V_2} dV_2 + \frac{\partial E_{23}}{\partial V_3} dV_3 \\ dE_3 &= \frac{\partial E_{31}}{\partial V_1} dV_1 + \frac{\partial E_{32}}{\partial V_2} dV_2 + \frac{\partial E_{33}}{\partial V_3} dV_3 \end{aligned}$$

where the single subscripts correspond to three variables and three errors and where the double subscripts indicate the change in a particular error (first subscript) due to a change in a particular variable (second subscript).

Assuming small changes results in the following approximations (where B refers to a base value):

$$\begin{aligned} dE &= E - EB \\ dV &= V - VB \\ \frac{\partial E}{\partial V} &= \frac{\Delta E}{\Delta V} \end{aligned}$$

With these approximations and the fact that E should be zero when the engine is balanced, the set of partial differential equations reduces to

$$\begin{aligned} E_1 - EB_1 &= \frac{\Delta E_{11}}{\Delta V_1} dV_1 + \frac{\Delta E_{12}}{\Delta V_2} dV_2 + \frac{\Delta E_{13}}{\Delta V_3} dV_3 = -EB_1 \\ E_2 - EB_2 &= \frac{\Delta E_{21}}{\Delta V_1} dV_1 + \frac{\Delta E_{22}}{\Delta V_2} dV_2 + \frac{\Delta E_{23}}{\Delta V_3} dV_3 = -EB_2 \\ E_3 - EB_3 &= \frac{\Delta E_{31}}{\Delta V_1} dV_1 + \frac{\Delta E_{32}}{\Delta V_2} dV_2 + \frac{\Delta E_{33}}{\Delta V_3} dV_3 = -EB_3 \end{aligned}$$

Three more passes (six for SMOTE) are now made through the engine cycle calculations, and one variable is changed by a small amount ( $\Delta V$ ) for each pass. The change in each error due to the small change in the variables ( $\Delta E/\Delta V$ ) can then be calculated.

The above set of differential equations can now be solved for  $dV_1$ ,  $dV_2$ , and  $dV_3$ , and, in general, the new value of each independent variable would be given by

$$V = V_B + dV$$

If the engine cycle calculations were linear functions, the engine would balance (errors equal zero) with these new values of the variables. However, this is not the case, and it is usually necessary to repeat the above process (where the new values become the base values) several times before a balance is obtained.

A subroutine to determine the solution of a matrix is used to solve the set of differential equations. After each pass through the engine, a matrix array is loaded with the appropriate values; after seven passes (base value plus six independent variables), the matrix subroutine is called to solve the matrix.

It was found that the "dV's" obtained from the solution of the differential equations were in many cases too large, thus causing the variables to exceed their limits, and to make it practically impossible to balance the cycle. The "dV's" are therefore multiplied by a suppression factor (presently 0.6) which limits the swing of the variables. In addition, if a suppressed "dV" is still greater than 5% of the value of the variable itself, it is reduced to the 5% value. Although this procedure may tend to increase the number of passes before balancing in some cases, it also balances points which previously would not balance. These points are most generally far from the design point, where oscillations of the dependent variables tend to build up.

## APPENDIX

### SAMPLE RESULTS

The following computer printouts are examples of typical output from SMOTE. The first point is the design point and includes a page of correction (or scaling) factors and a page of values of variables in common. The other points represent conditions throughout a flight envelope and consist of a primary page of output for each point. Not included for these points is a common dump, which normally follows each primary output page and is very similar to the common dump following the design point correction factors.

The engine cycle chosen was a mixed flow turbofan (bypass ratio of 1.4) with a convergent nozzle, a total airflow of 180 pounds a second, and a turbine inlet temperature ( $T_4$ ) of 2400°R. The points were run in a fixed  $T_4$  mode; that is, PCNC is an independent variable. Note that the nozzle area is recalculated at each afterburning point for optimum expansion and that no balancing occurs at these points.

SHOT DESIGN POINT

MAIN DESIGN	PAFCFM = 0.100000007E 01	BTAPCFM = 0.099999999E 01	WA1CFM = 0.100000003E 01	T20E = 0.510000020E 03
COMPRESSOR DESIGN	PRCCFM = 0.99977639E 00	BTACCFM = 0.10004494E 01	WA2CFM = 0.997388865E 00	T210E = 0.63224932E 03
COMBUSTOR DESIGN	WA2G03E = 0.13772073E 02	BTADCFM = 0.099999999E 01	OTC0CFM = 0.10178453E 01	
H.P. TURBINE DESIGN	CH1PCFM = 0.99939161E 00	TRHPCFM = 0.10000931E 01	OTR1PCFM = 0.099999999E 00	DRH1CFM = 0.10004254E 01
L.P. TURBINE DESIGN	CHLPCFM = 0.10002361E 01	TRLPCFM = 0.10002363E 01	OTL1PCFM = 0.099999999E 01	DHL1CFM = 0.99003777E 00
DUCT DESIGN	WA2303E = 0.13254201E 04			
TURBINE/DUCT AREA DESIGN	A95E = 0.20619599E 01	AH95E = 0.41298576E-00	A29E = 0.42450354E 01	AH29E = 0.17414913E-00
INTERDRAUGHT DESIGN	WA66C05E = 0.30173256E 04			
NOZZLE DESIGN	A0E = 0.277900084E 01	AH0E = 0.099999999E 01	A9E = 0.279600084E 01	AH9E = 0.099999999E 01
MAIN SONIC CONVERGENT NOZZLE	PAE = 0314.95	PN = 0214.95	SPCE = 0.61205	

COMMANDANT 1 LOOPS

AFAPL-TR-67-125  
Part I

SLS 1016

OUTPUT	AM= 0.	ALTP= 0.	T4= 1750.00	DTAN= 1.0000
PCNA	0.561653E 02	CNA 0.535E 00	2P 0.594640E 0C	PRF 0.126320E 01
PCNC	0.714276E 02	CNC 0.685658E 00	PRC 0.690779E 00	PRF 0.463760E 02
T2	0.51 468E 03	P2 0.100000E 01	T21 0.562700E 03	P21 0.281219E 02
PCBLP	0.	BLP 0.	BLLP 0.	BLUB 0.
PCBLIP	0.000000E 00	BLIP 0.136672E 01	BLIP 0.	BLUB 0.
WA3	WF6 0.410316E-00	WA4 0.327255E 02	WA4 0.120441E-01	WTAD 0.965372E 00
TMPLP	0.215719E 02	CNIP 0.170669E 01	DITCIP 0.477720E-01	DITCIP 0.030744E 02
TMPLP	0.466710E 02	CHLP 0.149019E 01	DITCIP 0.209477E-01	DITCIP 0.142146E 04
PCBLOU	0.200000E-00	DLOU 0.240180E-00	P24 0.564270E 03	P24 0.170447E 01
WAD	WID 0.	W024 0.626602E 02	PAR24 0.	WTAD 0.130693E 04
DTAC	0.03299E 00	DTAC 0.776100E 00	DTATIP 0.076100E 00	DTATIP 0.260364E-00
T6	0.036140E 03	P6 0.122907E 01	AK6 0.119935E 01	AK6 0.267904E 01
T7	WPA 0.	WC7 0.951944E 02	PAR7 0.430404E-02	WTAA 0.967944E 02
PSH	0.100000E 01	AM0 0.504652E 00	Y0 0.695767E 03	AM0 0.304652E 00
PSH	0.920	AM20 0.	PS29 0.	AM29 0.
HYPASS	0.103209E 01	WPT 0.	WPT 0.	WPT 0.
CVHNO2	0.914000E 00	VJH 0.65330E 03	CVHNO2 0.905000E 00	VJH 0.206179E 04
MAIN SUBSONIC CONVURG. M0111	P11 2061.79	P11 2061.79	P11 2061.79	SFC 0.7304

SLS MILITARY

OUTPUT	AM#	0.	ALT#	0.	T4#	2,000.00	T7#	1,000.00
PCN#	1.000000E 02	1.000000E 00	CH#	2E	PR#	WAFC	WA#	1.000000E 03
PCNC	1.000000E 02	0.001739E 00	CNC	2C	PR#	WACC	WAC	0.750000E 02
T2	0.510660E 03	1E 2	0.632249E 03	T21	P21	T3	P3	0.120000E 02
PCUL#	0.	0.100000E 01	PCUL#	PCUL#	ILC	PCUL#	ILC	0.
PCULP	0.	0.500000E 01	PCULP	0.372000E 01	PCUL#	0.	ILC	0.
PCULP	0.500000E 00	0.200000E 01	PCULP	0.	ILC	0.240000E 04	ILC	0.114000E 02
WA#	0.712900E 02	0.141359E 01	WA#	WA#	WA#	WA#	WA#	0.500000E 01
T#	0.212900E 02	0.204000E 01	CH#	0.50230E-01	0.190399E-01	0.983000E 00	0.192492E 04	0.432444E 01
T#	0.554100E 02	0.228000E 01	CH#	0.36015E-01	0.120659E 03	0.120659E 02	0.165352E 04	0.210630E 01
PCD#	0.200000E-00	0.750000E 00	BLD#	T24	P24	T23	P23	0.192000E 01
WAD	0.109720E 03	0.	WA24	WA24	WA24	WA24	WA24	0.400000E-01
BTAP	0.050000E 00	0.630000E 00	BTAC	BTAT#	BTAT#	AM#	AM#	AM#
T6	0.109311E 04	0.198870E 01	P6	AM#	AM#	V6	W6	W6
T7	0.109311E 04	0.	WA7	0.16992E 01	0.250644E-00	0.412227E 03	0.101414E 03	0.101414E 03
PS6	0.101949E 01	0.100000E 01	AM#	Y6	P#	AM#	V9	AM#
P326	0.	AM26	V26	P529	AM29	V29	0.	0.147629E 04
DYBASS	0.140000E 01	0.	HP#XT	W#T	W#T	V#	PR#	PR#
CVMH#2	0.989000E 00	0.145415E 04	V#M	CVMH#2	P#	P#M	0.019921E 04	0.115349E 03
MAIN SONIC CONVERGENT NO2210	F0#	0314.95	F#N#	0314.95	F#N#	0314.95	SFC#	0.01205

NOZZLE DIVISION

SLZ TAKE-OFF

AH= 0.40324220E 01 AHB= 0.90408222E 00 AG= 0.40324220E 01 AH9= 0.90408222E 00

OUTPUT AH= 0. ALTP= 0. T4= 2400.00 T7= 3200.00 UTAA= 1.00000

PCNP CHP 1F PAF WAF WAF 1.000000E 02 1.000000E 0C 0.033333E 00 0.200000E 01 0.100000E 03 0.100000E 03

PCNC CNC LC PRC WACC WAC 1.000000E 02 0.891739E 00 0.014999E 00 0.000000E 01 0.421627E 02 0.750000E 02

T2 T21 P21 T2 P2 0.910666E 03 0.100000E 01 0.032249E 03 0.200000E 01 0.116209E 04 0.120000E 02

PCBLP BLP PCBLC BLC PCBL0B BLOB 0. 0. 0. 0. 0. 0.

PCBLHP BLHP PCBLLP BLLP T4 P4 0. 0. 0. 0. 0. 0.

0.000000E 00 0.300000E 01 0. 0. 0. 0.200000E 04 0.114000E 02

WA3 WFB WFA WFA 0.712500E 02 0.141359E 01 0.726696E 02 0.198299E 01 0.950000E 00 0.500000E 01

TMHPH CHP DHTCHP DHTC DHTAB DCONH 0.212500E 02 0.204000E 01 0.940230E-01 0.129659E 03 0.102492E 04 0.422944E 01

TMFLP CHP DHTCLP DHTCP DHTAB DCONH 0.934100E 02 0.228000E 01 0.296015E-01 0.762299E 02 0.165532E 04 0.206300E 01

PCBL0U BLOU T24 P24 T25 P25 0.200000E-00 0.750000E 00 0.655951E 03 0.192000E 01 0.655951E 03 0.192000E 01

WAD WAD W024 MAR24 DTAD OPDUC 0.105750E 03 0. 0.105750E 03 0. 0. 0. 0.400000E-01

BTAP BTAC BTATHP BTATLP AH35 AH29 0.850000E 00 0.850000E 00 0.890000E 00 0.900000E 00 0.412024E-00 0.174134E-00

T6 P6 P56 AH6 V6 V9 0.105751E 04 0.198870E 01 0.189992E 01 0.258644E-00 0.412227E 03 0.161414E 03

T7 WFA W07 MAR7 DTAA DPART 0.320000E 04 0.705234E 01 0.186466E 03 0.470330E-01 0.910000E 00 0.399025E-01

V10 AH8 V8 PS9 AH9 V9 0.100000E 01 0.904082E 00 0.227120E 04 0.100000E 01 0.904082E 00 0.227120E 04

PS20 AH20 V28 PS29 AH29 V29 0. 0. 0. 0. 0. 0.

BYPASS BYPXT WFT WOT VA PRO 0.140000E 01 0. 0.846593E 01 0.168466E 03 0. 0.

CVWNO2 VJW CYDNO2 VJD PCW POP 0.985000E 00 0.223713E 04 0.985000E 00 0. 0.131044E 01 0. 0.

MAIN SUBSONIC CONVERG. NOZZLE P0= 13104.02

FPC= 2.32373

SET-UP LOW ALTITUDE DASH

OUTPUT	AM= 1.200	ALTP= 300.	T4= 2400.00	UTAA= 0.9915	
PCNPF	0.9243534E 02	0.735544E 00	0.495935E 00	WAMC HAP	
PCNC	0.922888E 02	0.772037E 00	0.737459E 00	WACC HAC	
T2	0.663864E 03	P2 0.236205E 01	T21 0.741138E 03	0.443942E 01 U.333410E 02	
PCBLF	0.	BLH 0.	PCBLG 0.500000E-01	0.321391E 01 U.32567E 04	
PCBLHP	0.	BLHP 0.	PCBLLP 0.	0.447029E 01 PCBL00 0.	
0.800000E 00	0.357623E 01	W04 0.865939E 02	BLLP 0. 0.440000E 04	0.125333E 02	
WA3	0.160384E 01	0.160384E 01	W04 0.100030E-01	0.965000E 00 0.514029E-01	
0.849359E 02	0.160384E 01	0.160384E 01	W04 0.100030E-01	0.965000E 00 0.514029E-01	
TFLHP	0.212289E 02	0.1682209E 01	DMTCHP 0.517622E-01	DMTC 0.124323E 03	DMTC 0.194444E 04
TFPLP	0.516314E 02	0.169223E 01	DTTCP 0.290705E-01	DTTF 0.566936E 02	DTTF 0.174336E 04
PCBLU	0.200000E-01	BLU 0.894058E 00	T24 0.743465E 03	P24 0.303802E 01	T24 0.743465E 03
WAD	0.	WFD 0.	W024 0.192539E 03	W024 0. 0.462942E-01	W024 0.
WTAN	0.808624E 00	BTAC 0.760999E 00	BTATLP 0.883900E 00	BTATLP 0.898767E 00	BTATLP 0.224506E-00
T4	0.101268E 04	P6 0.308446E 01	PS6 0.295119E 01	AM6 0.257627E-00	AM6 0.409007E 03
0.157016E 01	0.100000E 01	W07 0.146886E 04	W07 0.157801E 01	W07 0.100000E 01	W07 0.202675E 03
P528	0.	AM20 0.	V28 0.	PS29 0.	AM29 0.
0.	0.	WPEXT 0.160384E 01	WPT 0.160384E 01	WOT 0.282675E 03	WOT 0.398077E-01
BYPASS	0.214774E 01	WVH 0.985000E 00	CVDNCL 0.985000E 00	VJD 0.	VJD 0.116895E 03
CVDNCL	0.985000E 00	WVH 0.144664E 04	CVDNCL 0.985000E 00	VJD 0.	VJD 0.127099E 05
MAIN SONIC CONVENTIONAL NOZZLE	PG= 16236.07	PN= 4946.59	PN= 4946.59	PG= 1.26992	PG= 1.26992

LOW ALTITUDE DASH

A8= 0.59879597E 01 AM8= 0.09999999E 01 A9= 0.59879597E 01 AM9= 0.09999999E 01

NOZZLE DESIGN

OUTPUT	AH=	ALT=	ALT_P=	500.	74=	2400.00	77=	3200.00	ETAR=	0.9915
PCNF	CHF	2F			PRF		WAFC		WAF	
0.893554E 02	0.736346E 00	0.4935339E-00		0.136063E 01	0.1346029E 03		0.281071E 03			
PCNC	CHC	2C		PRC		WACC		WAC		
0.922088E 02	0.772037E 00	0.737659E 00		0.443942E 01	0.223610E 02		0.894038E 02			
T2	P2	T21		P21	T2	P3				
0.665884E 03	0.232205E 01	0.741198E 03		0.321391E 01	0.122367E 04		0.142679E 02			
PCBLF	BLF	PCBLFC		BLC	PCALOB					
0.	0.	0.500000E-01		0.447029E 01	0.	0.				
PCBLHP	BLHP	PCBLLP		BLLP	T4	P4				
0.800000E 00	0.257623E 01	0.		0.	0.240000E 04	0.135333E 02				
WA3	WFO	WFO		PAR4	ETAB	OPCOM				
0.847355E 02	0.160284E 01	0.885394E 02		0.160830E-01	0.985000E 00	0.914829E-01				
TRFHP	CNIP	DNICHP		DNICHP	T5	P5				
0.213285E 02	0.188269E 01	0.517902E-01		0.126323E 03	0.194440E 04	0.521690E 01				
TRFLP	CHLP	DNICLP		DNICLP	T5	P5				
0.518314E 02	0.189323E 01	0.290705E-01		0.566956E 02	0.174336E 04	0.315740E 01				
PCBLDU	BLDU	T24		P24	T25	P25				
0.200000E-00	0.894058E 00	0.743465E 03		0.305882E 01	0.733465E 03	0.305882E 01				
WAD	WFD	W024		PAR24	ETAD	OPUC				
0.192359E 03	0.	0.192359E 03		0.	0.	0.483542E-01				
ETAR	ETAC	ETATIP		ETATLP	AM95	AM25				
0.808626E 00	0.780989E 00	0.880980E 00		0.898707E 00	0.324506E-00	0.214069E-00				
T6	P6	P56		AM6	V6	W6				
0.108126E 04	0.208646E 01	0.295119E 01		0.257627E-00	0.4049007E 03	0.282673E 03				
T7	WFA	W07		PAK7	UTAA	OPART				
0.320000E 04	0.110545E 02	0.293729E 03		0.450361E-01	0.910000E 00	0.398077E-01				
PS8	AM8	V8		PS9	AM9	V9				
0.140201E 01	0.100000E 01	0.246577E 04		0.140201E 01	0.100000E 01	0.246577E 04				
PS28	AM28	V28		PS29	AM29	V29				
0.	0.	0.		0.	0.	0.				
DYPA55	HP0XT	WPT		WOT	VA	HRD				
0.214377E 01	0.	0.126503E 02		0.293722E 03	0.133009E 04	0.116893E 03				
CWNH02	VJW	CWNH02		VJD	PGH	FUP				
0.985000E 00	0.244648E 04	0.9090000E 00		0.	0.223932E 05	0.532134E 04				
MAIN SONIC CONVERGENT NOZZLE	P0= 27674.70	PN= 15905.22				SFC= 2.09076				

SUPERSONIC CRUISE

OUTPUT	AH#	0.800	ALTP#	36100.	T4#	2100.00						
PCNHF	0.931973E 02	0.101170E 01	CNAF	2F	PRF	WANC	ETARR#	1.00000				
PCNHC	0.933169E 02	0.090000E 00	CNC	2C	PRC	WACC	MAP	0.674723E 02				
T2	0.440000E 03	0.240355E-00	P2	T21	P21	WAC	WAC	0.205406E 02				
PCBLF	0.	0.	BLF	PCOLC	DLC	PCOLCD	PCOLCD	0.	P3	0.10032E 04	0.22610E 01	
0.	0.	0.	0.	0.900000E-01	0.142703E 01	0.	0.	0.	0LNIS	0.		
PCBLHP	0.	0.	BLHP	PCBLLP	BLLP	T4	T4	P4				
0.000000E 00	0.114163E 01	0.	0.	0.	0.	0.210000E 04	0.40432E 01					
WA3	0.271136E 02	0.450000E-00	WFB	W04	PAR4	CTAD	OPCDH					
0.212556E 02	0.203910E 01	0.	0.275723E 02	0.169243E-01	0.960707E 00	0.900209E-01						
TFPHP	0.	0.	CNHP	DHTCHP	DHTC	T5	T5	P5				
0.200000E-00	0.285406E-00	0.	0.541622E-01	0.113732E 03	0.167224E 04	0.146920E 01						
WAD	0.	WFD	CNLP	DHTCLP	DHTF	T5	T5	P55				
0.942355E 03	0.69392E 00	0.	0.401773E-01	0.669031E 02	0.142664E 04	0.733033E 00						
PCBLDU	0.	BLDU	T24	P24	T25	P25	P25					
0.392357E 02	0.	0.	0.562353E 03	0.666524E 00	0.562353E 03	0.666524E 00						
ETAP	0.037913E 00	0.020109E 00	07AC	ETATHP	ETAILP	AM35	AM25					
T6	0.	P6	W024	PAR24	CTAD	OPDUC	OPDUC					
0.942355E 03	0.69392E 00	0.	0.392371E 02	0.	0.	0.	0.396014E-01					
PSD	0.352897E-00	0.000000E 01	WA	W07	PART	CTAA	OPART					
PS2d	0.	AM28	V20	P529	AM29	AM29	AM29					
0.	0.	0.	0.	0.	0.	0.	0.					
BYPASS	0.	HPEXT	WAT	WOT	VA	FRD	FRD					
0.136476E 01	0.	0.	0.450000E-00	0.679512E 02	0.774794E 03	0.162531E 04						
CWNOC	0.985000E 00	0.135159E 04	CWNOC	CWNOC	VJD	FGH	FGP					
MAIN SONIC CONVERGENT NOZZLE	PN#	3621.69	PN#	1996.38	PN#	1996.38	SFC#	0.0274.9				

SUPERSONIC AT MILITARY MACH

OUTPUT	AM= 1.200	ALTP= 50000.	T4= 2400.00				
PCMP	CMP	1P	PAF	WAPC	WAP		ETAR= 0.9915
0.100191E 03	0.101749E 01	0.855547E 00	0.206600E 01	0.183700E 03	0.512534E 02		
PCM	CNC	2C	PAC	WACC	WAC		
0.100012E 03	0.898671E 00	0.822625E 00	0.613671E 01	0.428047E 02	0.216175E 02		
T2	P2	T21	P21	T3	P3		
0.502712E 03	0.275217E-00	C.642094E 03	0.568597E 70	0.115396E 04	0.346932E 01		
PCBLPF	BLP	PCBLIC	BLIC	PCBLUD	BL08		
0.	0.	0.500000E-01	0.109088E 01	0.	0.		
PCBLHP	BLHP	PCBLLP	BLLP	T4	P4		
0.800000E 00	0.827200E 00	0.	0.	0.240000E 04	0.331539E 01		
WA3	W6	W04	PAR4	BTAB	DPCDM		
0.207265E 02	0.417850E-00	0.211445E 02	0.201000E-01	0.975313E 00	0.498460E-01		
TPHP	CNHP	04TCHP	0HTC	T5	P5		
0.212515E 02	0.204025E 01	0.541369E-01	0.130008E 03	0.192371E 04	0.122601E 01		
TPFLP	CNLP	0HTCLP	0HTP	T55	P55		
0.535194E 02	0.228507E 01	0.403946E-01	0.779472E 02	0.164620E 04	0.398371E 00		
PCBLDU	BLDU	T24	P24	T25	P25		
0.200000E-00	0.216179E-00	0.640371E 03	0.546261E 00	0.645937E 03	0.546261E 00		
WAD	WFD	W024	PAR24	ETAD	DPOUC		
0.997541E 02	0.	0.295441E 02	0.	0.	0.-24636E-01		
BTAP	BTAC	BTATHP	ETAILP	AM55	AM25		
0.30473E 00	0.827917E 00	0.819763E 00	0.897465E 00	0.423142E-00	0.170720E-00		
T6	P6	PS6	AM6	V6	W6		
0.109268E 04	0.565981E 00	0.540570E 6	C.259374E-00	0.413274E 01	0.517713E 02		
T7	WFA	W07	PAR7	ETAA	DPAFT		
0.109268E 04	0.	0.517713E 02	0.813675E-02	0.	0.400840E-01		
PS8	AH8	V8	PS9	AM9	V9		
0.290912E-00	0.100000E 01	0.147597E 04	0.290912E-00	0.100000E 01	0.147597E 04		
PS28	AH28	V28	PS29	AM29	V29		
0.	0.	0.	0.	0.	0.		
BYPASS	MPEXT	WPT	W07	V4	PRU		
0.135377E 01	0.	0.417850E-00	0.517713E 02	0.116219E 04	0.105499E 04		
CVHNO2	VJH	CVHNO2	VJD	FGH	FGP		
0.985000E 00	0.145363E 04	0.985000E 00	0.	0.233936E 04	0.104409E 04		
MAIN SONIC CONVERGENT NOZZLE	PN# 3303-44	PN# 1220-43	PN# 1220-43	SFC# 0.98417			

## SET-UP SUPERSONIC WITH AN TURBOURBINE

NOZZLE DIRECTION		AUX 0.36070030 01		AUX 0.00000000 01		AUX 0.36070030 01		AUX 0.00000000 01		AUX 0.36070030 01		AUX 0.00000000 01	
SUPERSONIC PARTIAL A:0													
OUTPUT	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000	AUX 1.0000		
PCNHP	0.9091336 02	0.04064440 00	0.60327411 00	0.1625490 01	PCNHP	0.9091336 02	0.04064440 00	0.60327411 00	0.1625490 01	PCNHP	0.9091336 02		
PCNHC	0.9701768 02	0.03084456 00	0.7006632 03	0.3252378 01	PCNHC	0.9701768 02	0.03084456 00	0.7006632 03	0.3252378 01	PCNHC	0.9701768 02		
T2	0.2702940 03	0.4401204-00	T21	0.6042090 03	T21	0.2702940 03	0.4401204-00	T21	0.6042090 03	T21	0.2702940 03		
PCNLP	0.	0.	PCNLP	0.3000000-01	PCNLP	0.	0.3000000-01	PCNLP	0.	PCNLP	0.		
PCNLLP	0.0000000 00	0.9999645 00	PCNLLP	0.	PCNLLP	0.0000000 00	0.9999645 00	PCNLLP	0.	PCNLLP	0.		
WA2	0.2373960 02	0.6293020-00	WA4	0.2117091 02	WA4	0.2373960 02	0.6293020-00	WA4	0.2117091 02	WA4	0.2373960 02		
WA5	0.2120638 02	0.1979168 01	WA7	0.5354330-01	WA7	0.2120638 02	0.1979168 01	WA7	0.5354330-01	WA7	0.2120638 02		
WA6	0.5325700 02	0.2661639 01	WA8	0.3461635-01	WA8	0.5325700 02	0.2661639 01	WA8	0.3461635-01	WA8	0.5325700 02		
PCNLUU	0.000 000-00	0.2391910-00	PCNLUU	0.6973090 03	PCNLUU	0.000 000-00	0.2391910-00	PCNLUU	0.6973090 03	PCNLUU	0.000 000-00		
WA9	0.2661330 02	0.	WA9	0.024	WA9	0.2661330 02	0.	WA9	0.024	WA9	0.2661330 02		
WA10	0.6447100 00	0.0374610 00	WA10	0.0070906 00	WA10	0.6447100 00	0.0374610 00	WA10	0.0070906 00	WA10	0.6447100 00		
T6	0.	0.	T6	0.56	T6	0.	0.	T6	0.56	T6	0.		
0.1006700 04	0.7392170 00	0.1006700 04	0.7392170 00	0.7392170 00	0.1006700 04	0.1006700 04	0.7392170 00	0.1006700 04	0.7392170 00	0.1006700 04	0.7392170 00		
T7	0.1700000 04	0.6495740 00	T7	0.6049540 02	T7	0.1700000 04	0.6495740 00	T7	0.6049540 02	T7	0.1700000 04		
AM0	0.359740-00	0.1000000 01	AM0	Y6	AM0	0.359740-00	0.1000000 01	AM0	Y6	AM0	0.359740-00		
AM20	0.	AM20	V20	0.	AM20	0.	AM20	V20	0.	AM20	0.		
HYDROX	0.	HYDROX	W17	HYDROX	0.	HYDROX	0.	HYDROX	W17	HYDROX	0.		
0.1690001 01	0.	0.1104000 01	0.6164946 02	0.1690001 01	0.1104000 01	0.6164946 02	0.1690001 01	0.1104000 01	0.6164946 02	0.1690001 01	0.1104000 01		
CYANOID	0.9192000 00	0.1003000 04	CYANOID	0.9092000 00	CYANOID	0.9192000 00	0.1003000 04	CYANOID	0.9092000 00	CYANOID	0.9192000 00		
MAIN SHMIC CONVERGENT NOZZLE	0.000 000-43	MAIN SHMIC CONVERGENT NOZZLE											

NOZZLE DURATION		SUSTAINING MULL A/H		A/H 0.09612714 01		A/H 0.0799999999999999 01		A/H 0.09612714 01		A/H 0.0799999999999999 01	
OUTPUT		ALT: 00000	ALT: 00000	TA: 2400.00	TA: 2400.00	TA: 2400.00	TA: 2400.00	TA: 2400.00	TA: 2400.00	TA: 2400.00	TA: 2400.00
PCNHP	0.04044440 00	CNC	0.6035740 00	PHF	0.1625891 01	WAC	0.1935770 03	WAC	0.1935770 03	WAC	0.1935770 03
PCNHC	0.03055450 00	CNC	0.7006630 00	PHC	0.9232376 01	WAC	0.3605110 02	WAC	0.3605110 02	WAC	0.3605110 02
T4	0.21	T21	0.6942051 03	P21	0.7009240 00	T3	0.1197010 04	T3	0.3796630 01	T3	0.3796630 01
PCNHL	0.	PCNLC	0.	WLC	0.	WCHWD	0.	WCHWD	0.	WCHWD	0.
PCNLLP	0.	PCNLLP	0.	WLLP	0.	WLLP	0.	WLLP	0.	WLLP	0.
0.00000000 00	0.99999999 00	WAD	0.2499450 01	TA4	0.23000000 04	TA4	0.3793690 01	TA4	0.3793690 01	TA4	0.3793690 01
0.2373961 02	0.4593025 00	WAD	0.2619091 02	WAD	0.1934750 01	WAD	0.927420 00	WAD	0.927420 00	WAD	0.927420 00
T55511P	0.2120630 02	WHTCHP	0.5256331 01	WHTC	0.1206310 03	T5	0.1929240 04	T5	0.1929240 04	T5	0.1929240 04
T55511P	0.5321790 02	CNLH	0.3461638 01	WHTCLP	0.0660961 02	T55	0.1691410 04	T55	0.1691410 04	T55	0.1691410 04
PCBLDU	0.20000000 00	DLDU	0.6977307 03	DLU	0.7276320 00	DL5	0.6973090 03	DL5	0.6973090 03	DL5	0.6973090 03
WAD	0.	WAD	W024	WAD	WAD	WAD	WAD	WAD	WAD	WAD	WAD
0.4205130 02	0.	WTAP	0.4205130 02	WTAP	0.	WTAP	0.	WTAP	0.	WTAP	0.
0.0447903 00	0.0074610 00	WTAP	0.0074610 00	WTAP	0.0074610 00	WTAP	0.0074610 00	WTAP	0.0074610 00	WTAP	0.0074610 00
T6	0.752170 00	P6	0.7101000 00	P6	0.3579230 00	AH6	0.4100350 03	AH6	0.4100350 03	AH6	0.4100350 03
T7	0.3200000 01	WPA	0.2660040 01	W67	0.4607970 01	PAR7	0.700000 00	PAR7	0.700000 00	PAR7	0.700000 00
130	0.3301290 00	AHD	0.1000000 01	Y0	0.3301290 00	P50	0.100000 01	AH9	0.100000 01	AH9	0.100000 01
P320	0.	AM26	V20	P320	0.	AM29	0.	AM29	0.	AM29	0.
0.	0.	WHT	0.	WHT	0.	V29	0.	V29	0.	V29	0.
DYPASS	0.	WHT	0.	WHT	0.	V29	0.	V29	0.	V29	0.
0.1696600 01	0.	0.3101140 01	0.7009250 02	0.7009250 02	0.1549990 04	VAD	0.3245710 04	VAD	0.3245710 04	VAD	0.3245710 04
CYHNOZ	0.9890000 00	VJW	0.9890000 00	VJD	0.	POH	0.5564320 04	POH	0.5564320 04	POH	0.5564320 04
MAIN SONIC CONVERGENT NOZZLE	FM 0186.04	FM	4940.33	FM	4940.33	FM	5PC 2.26205	FM	5PC 2.26205	FM	5PC 2.26205

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11 SUPPLEMENTARY NOTES	12 SPONSORING MILITARY ACTIVITY Air Force Aero Propulsion Laboratory Wright-Patterson Air Force Base, Ohio 45433	
13 ABSTRACT  This report describes a digital computer program titled SMOTE (Simulation of Turbofan Engine). SMOTE is a computer program for balancing-cycle turbofan engines capable of running both design and off-design points. Component performance maps are reduced to Block Data (tabular form) to provide a base for calculating component performance. The design point is run first and map correction factors are calculated to scale the components to the desired performance. These correction factors are then applied to the component performance maps at off-design points. Initially, when the program is running at an off-design point, the cycle is not balanced, and errors (for example, work required by the compressor minus work supplied by the turbine) are generated. Small changes in engine independent variables (for example, compressor speed) then produce small changes in the errors, and these differential changes are loaded into a matrix. The matrix is then solved for the set of independent variables which results in zero errors, thus balancing the cycle. Actually, this process may be repeated several times before it reaches a balanced point because there is a non linear relationship between the independent variables and the errors. Sample results are included in this report.  (Distribution of this abstract is unlimited.)		

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